

1.[5]

(a)

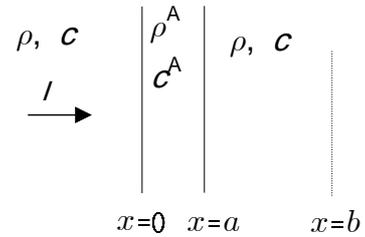
가 가

($x=0$)

$$(\sigma_x)_i = f\left(t - \frac{x}{c}\right)$$

$$(\dot{u})_i = -\frac{1}{\rho c} f\left(t - \frac{x}{c}\right)$$

$x=b$



2.[6]

(dynamic elasticity)

stress equation of motion

$$\tau_{ij,j} = \rho \ddot{u}_i \quad \dots$$

stress-strain relation

$$\tau_{ij} = \lambda \epsilon_{kk} \delta_{ij} + 2 G \epsilon_{ij} \quad \dots$$

strain-displacement relation

$$\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}) \quad \dots$$

(a)

(displacement equation of motion)

1) $\nabla \cdot \tau = \rho \ddot{\mathbf{u}}$

2) $\tau_{ij} = \lambda \epsilon_{kk} \delta_{ij} + 2 G \epsilon_{ij}$

3) $\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$ (longitudinal wave)

(b) xyz

$u(x, y, z, t), v(x, y, z, t), w(x, y, z, t)$

1) $i = 2, j = 2$

2) $i = 2, j = 1$

3) $i = 1, j = 2$

3.[8]

(homogeneous),

(isotropic),

(linearly elastic)

$$G \nabla^2 \mathbf{u} + (\lambda + G) \nabla \nabla \cdot \mathbf{u} = \rho \ddot{\mathbf{u}}$$

$$\left(\nabla = i_1 \frac{\partial}{\partial x_1} + i_2 \frac{\partial}{\partial x_2} + i_3 \frac{\partial}{\partial x_3} \right)$$

(plane wave)

2 가

(a)

$$\mathbf{u} = f(\mathbf{x} \cdot \mathbf{p} - ct) \mathbf{d}, \quad \mathbf{p} \cdot \mathbf{p} = 2$$

(b)

$$\text{potential } \mathbf{u} = \phi + \mathbf{x} \times \Psi, \quad \mathbf{x} \cdot \mathbf{x} = 2$$

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4.[6] 2

(axial shear motion)

$w(r, t)$

(a) Newton

2

(equilibrium)

,

(b)

(strain)

$\epsilon_r, \epsilon_\theta, \epsilon_z, \gamma_{\theta z}, \gamma_{zr}, \gamma_{r\theta}$

(stress)

$\sigma_r, \sigma_\theta, \sigma_z, \tau_{\theta z}, \tau_{zr}, \tau_{r\theta}$

0

w

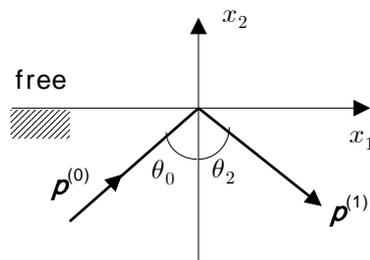
(shear modulus) G

, (a)

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1. [2] mode conversion
 가 .

2. [8] (,) 가 $x_2 = 0$
 가 $x_2 = 0$ θ_0 .



(a) $x_2 = 0$. $u^{(0)} = A_0$

$$(\sin\theta_0 \hat{i}_1 + \cos\theta_0 \hat{i}_2) \exp[i k_0 (x_1 \sin\theta_0 + x_2 \cos\theta_0 - c_L t)]$$

, $u^{(1)} = A_1 \cos(k_1 x_1 - \omega_1 t)$.

(b) $\sigma_2^{(0)}$ $\sigma_2^{(1)}$ (a)

(c) $x_2 < 0$ σ_2 $\sigma_2^{(0)}$, $A_1, k_1, \theta_1 = A_0$,
 k_0, θ_0 .

(d) $\theta_0 = 0$ ()

3. [3] (wavenumber) k 가 , ω 가
 c_g , u . group velocity
 phase velocity c wavenumber k

$$u = A \sin(k_1 x - \omega_1 t) + A \sin(k_2 x - \omega_2 t)$$

4.[4] SH-wave

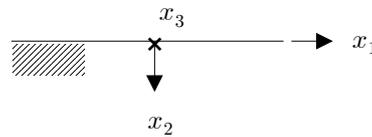
$$\frac{\partial^2 u_3}{\partial x_1^2} + \frac{\partial^2 u_3}{\partial x_2^2} = \frac{1}{c_T^2} \frac{\partial^2 u_3}{\partial t^2}$$

$$u_3 = A \exp(-b x_2) \exp[i k (x_1 - ct)]$$

(homogeneous)

SH-wave

가



5.[8] $x_2 = 0$

x_1

Rayleigh

$\phi, \psi (= \psi_3)$

u_1, u_2

$$u_1 = \frac{\partial \phi}{\partial x_1} + \frac{\partial \psi}{\partial x_2}, \quad u_2 = \frac{\partial \phi}{\partial x_2} - \frac{\partial \psi}{\partial x_1}$$

(a) x_2

σ_2

τ_{21}

u_1, u_2

$$\sigma_2 = \lambda \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} \right) + 2G \frac{\partial u_2}{\partial x_2} \quad \tau_{21} = G \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right)$$

(b)

$$\frac{\partial^2 \phi}{\partial x_1^2} + \frac{\partial^2 \phi}{\partial x_2^2} = \frac{1}{c_L^2} \frac{\partial^2 \phi}{\partial t^2} \quad \frac{\partial^2 \psi}{\partial x_1^2} + \frac{\partial^2 \psi}{\partial x_2^2} = \frac{1}{c_T^2} \frac{\partial^2 \psi}{\partial t^2}$$

$\Phi(r) \quad \Psi(r)$

(, p^2

$$= k^2 - \omega^2/c_L^2, \quad q^2 = k^2 - \omega^2/c_T^2 \quad)$$

(c)

$\sigma_2 \quad \tau_{21}$

$$\Phi(x_2) = A_1 \exp(-p x_2) + A_2 \exp(+p x_2)$$

$$A_2 = 0, \quad A_1 = A$$

$$\Psi(x_2) = B_1 \exp(-q x_2) + B_2 \exp(+q x_2)$$

$$B_2 = 0, \quad B_1 = B$$

(d)

가

$$4 k^2 p q - (k^2 + q^2)^2 = 0$$

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