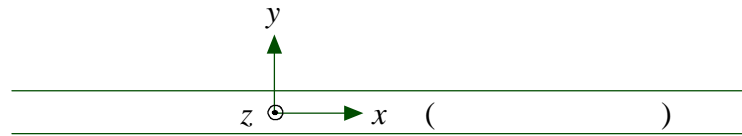


1. (, ,) , xz 가 .

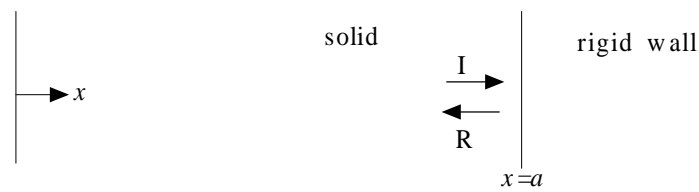


(a) $(\sigma_x, \sigma_y, \sigma_z)$, $(\epsilon_x, \epsilon_y, \epsilon_z)$, Hooke
 , Newton 2
 , c_p Young E , Poisson

$$\frac{\partial^2 u}{\partial x^2} = \frac{1}{c_p^2} \frac{\partial^2 u}{\partial t^2}$$

(b) (solution) .

2. $+x$ 1 $x=a$



(a) $(\sigma_x)_i = f(t - \frac{x}{c_L})$

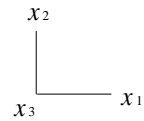
(b) $(u)_i = F(t - \frac{x}{c_L})$

3. (dynamic elasticity)

stress equation of motion $\tau_{ij,j} = \rho \ddot{u}_i$

stress-strain relation $\tau_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2 G \varepsilon_{ij}$

strain-displacement relation $\varepsilon_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i})$



(a) x_3 x_1-x_2 antiplane shear wave

(b) x_1-x_2 plane strain longitudinal wave

$$G u_{\alpha,\beta\beta} + (\lambda + G) u_{\beta,\beta\alpha} = \rho \ddot{u}_\alpha \quad (\alpha, \beta = 1, 2)$$

xyz $u(x,y,t)$ $v(x,y,t)$

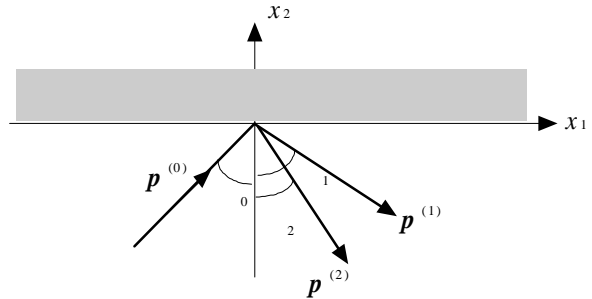
1. (12) SV 가 $x_2 < 0$

가, $x_2 = 0$

. $x_2 > 0$

(rigid)

$x_2 = 0$



(a) $x_2 = 0$

$$A_0 (-\cos \theta_0 \mathbf{i}_1 + \sin \theta_0 \mathbf{i}_2) \exp[i k_0 (x_1 \sin \theta_0 + x_2 \cos \theta_0 - c_T t)]$$

$$\mathbf{u}^{(0)} =$$

$$\mathbf{u}^{(1)}, \mathbf{u}^{(2)} = A_1, k_1, \theta_1, A_2, k_2, \theta_2$$

(b) $x_2 < 0$

$$\mathbf{u}^{(1)}, \mathbf{u}^{(2)}$$

\mathbf{u}

$$\mathbf{u}^{(0)}$$

$$k_1, \theta_1, k_2, \theta_2$$

(c)

$$\frac{A_1}{A_0} = \frac{A_2}{A_0}$$

(d) $\theta_0 = 0$

()

2. (12)

(,)

(G)

(torsional wave)가

$$v(r, z, t)$$

(free)

(a)

가

$$\frac{\partial \tau_{r\theta}}{\partial r} + \frac{2}{r} \tau_{r\theta} + \frac{\partial \tau_{\theta z}}{\partial z} = \rho \frac{\partial^2 v}{\partial t^2}$$

(b)

$$\exp[i(kz - \omega t)]$$

$$R(r)$$

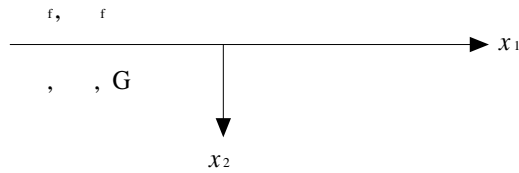
$$v(r, z, t) = R(r)$$

(c) $k = \omega / c_T$,

phase velocity

(d) $k = \omega / c_T$,

phase velocity



(a) Rayleigh (x_1, x_2, t) (x_1, x_2, t)
 c_T Lamé c_L

(b) $u_1(x_1, x_2, t)$
 c_T

(c) $u_1(x_1, x_2, t) = u_1(x_2) \exp[i(kx_1 - \omega t)]$
 $u_2(x_1, x_2, t) = u_2(x_2) \exp[i(kx_1 - \omega t)]$
 $\tau(x_1, x_2, t) = \tau(x_2) \exp[i(kx_1 - \omega t)]$

$$k^2 - \frac{\omega^2}{c_L^2} = p^2, \quad k^2 - \frac{\omega^2}{c_T^2} = q^2, \quad \frac{\omega^2}{c_f^2} - k^2 = s^2$$

* $u_1 = A \exp(-px_2), \quad u_2 = B \exp(-qx_2),$

$\tau = C \exp(-isx_2)$

(d) $x_2=0$

(e) $u_2, u_2^f, \tau, \tau^f, \tau_{21}, \tau_{21}^f$
 , (*)

(f) (e)

(g) (f) 0 ?

$$4 k^2 p q - (k^2 + q^2)^2 = ?$$

(h) wavenumber k $(k_R + i k_I)$