기계진동학 도전문제(제3장)

출처 및 해답 [수업지정도서 (중앙도서관 5층 디지털미디어룸 내)]

- [1] S. G. Kelly, Fundamentals of Mechanical Vibrations, 2nd ed., McGraw-Hill, 2000.
- [2] L. Meirovitch, Fundamentals of Vibrations, McGraw-Hill, 2001.
- [3] 이시복 등 8인 공역, 기계진동학, 제6판, 퍼스트북, 2019.

(원서 : S. S. Rao, Mechanical Vibrations, Prentice Hall, 2017.)

3.1 충격하중 응답 [3] Ex. 4.8

EXAMPLE 4.8 Response of a Structure Under Impact

In the vibration testing of a structure, an impact hammer with a load cell to measure the impact force is used to cause excitation, as shown in Fig. 4.8(b). Find the response of the system. m=5 kg, k=2 kN/m, c=10 N·s/m and F(t)=20 $\delta(t)+10$ $\delta(t-0.2)$ N,

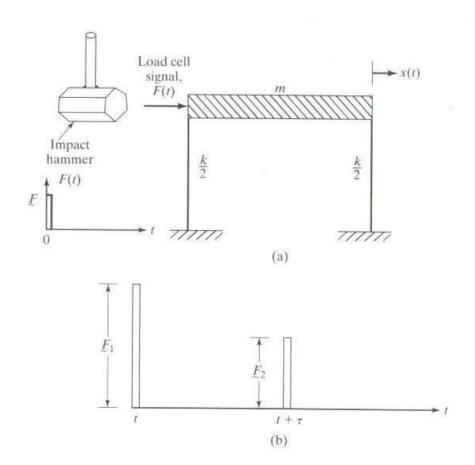


FIGURE 4.8 Structural testing using an impact hammer.

EXAMPLE 4.12 Compacting Machine Under Linear Force

Determine the response of the compacting machine shown in Fig. 4.13(a) when a linearly varying force (shown in Fig. 4.13(b)) is applied due to the motion of the cam. (Assume c=0)

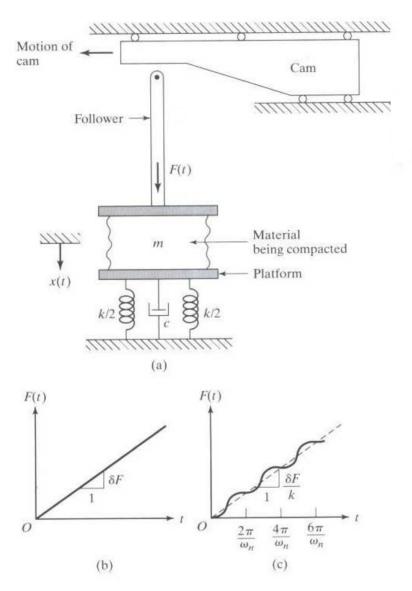


FIGURE 4.13 Compacting machine subjected to a linear force.

EXAMPLE 4.4 Periodic Vibration of a Hydraulic Valve

In the study of vibrations of valves used in hydraulic control systems, the valve and its elastic stem are modeled as a damped spring-mass system, as shown in Fig. 4.4(a). In addition to the spring force and damping force, there is a fluid pressure force on the valve that changes with the amount of opening or closing of the valve. Find the steady-state response of the valve when the pressure in the chamber varies as indicated in Fig. 4.4(b). Assume k = 2,500 N/m, c = 10 N·s/m, and m = 0.25 kg.

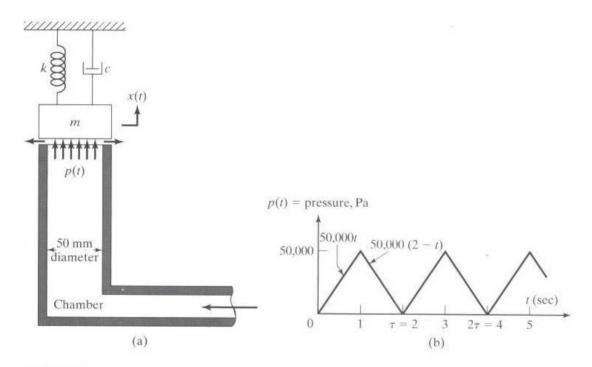


FIGURE 4.4 Periodic vibration of a hydraulic valve.

3.4 변환법 [3] Ex. 4.26

EXAMPLE 4.26 Step Response of a Compacting Machine

Find the response of the compacting machine of Fig. 4.10(a) assuming the system to be underdamped (i.e. $\zeta < 1$) and using Laplace transform technique.

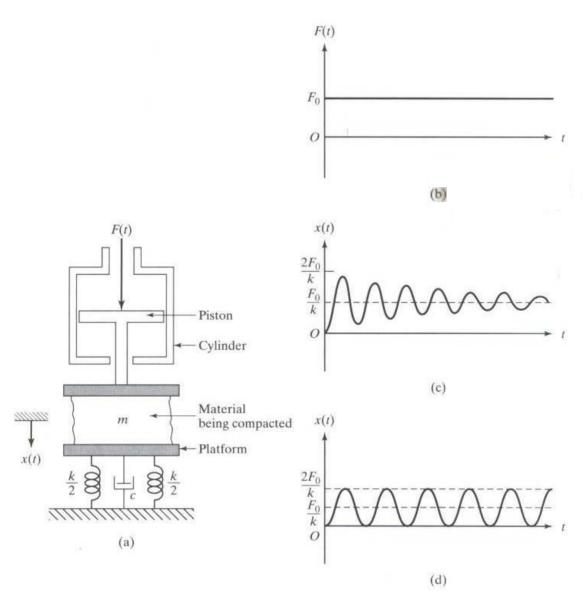


FIGURE 4.10 Step force applied to a compacting machine.

정 답

- 3.1 충격하중 응답
- [3] Example 4.8

$$x(t) = 0.200 \ e^{-t} \sin 19.98t + 0.1001 \ e^{-(t-0.2)} \sin 19.98(t-0.2) \ \Phi(t-0.2)$$
 m

- **3.2** 임의의 가진에 대한 응답 [3] Example 4.12

$$x(t) = \frac{\delta F}{k} \frac{1}{\omega_n} [\omega_n t - \sin \omega_n t]$$

- **3.3** 주기적 가진에 대한 응답 [3] Example 4.4

$$x_p(t) = 0.01964 - 0.01593 \cos(\pi t - 0.01257) - 0.001783 \cos(3\pi t - 0.0380) \quad \text{m}$$

3.4 변환법

[3] Example 4.26

ζ=()일 때

$$x(t) = \frac{F_0}{k} \left[\cos \omega_n (t - t_0) - \cos \omega_n t \right] + x_0 \cos \omega_n t + \frac{\dot{x}_0}{\omega_n} \sin \omega_n t$$